

↳ With $U = (|\phi_1\rangle, \dots, |\phi_x\rangle)$ ($d \times x$)-matrix,
project operators such as $H_A \rightarrow \tilde{H}_A = U^\dagger H_A U$

$\uparrow$
 $d \times d$ matrix

$x \times x$ matrix

(and possible other operators to be "measured") down
to the truncated space.

↳ Proceed likewise for ρ_B (or use reflection symmetry)

↳ Identify $\tilde{H}_A \rightarrow H_A$, $\tilde{H}_B \rightarrow H_B$ and restart
by adding two new sites.

↳ Iterate until $\frac{E}{N}$ becomes stationary and thus

represents the ground state energy per site of an infinite system.

→ For other operators (such as correlation functions) keep a large distance from the boundaries to avoid finite size effects.

- Computational cost of "infinite" DMRG:

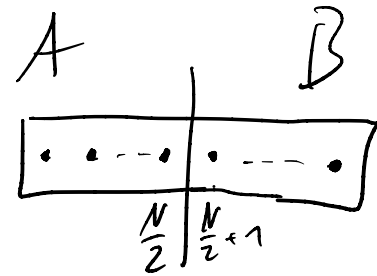
$$\mathcal{O}(N(d\chi)^3), \text{ memory } \mathcal{O}((d\chi)^2).$$

↑
sites

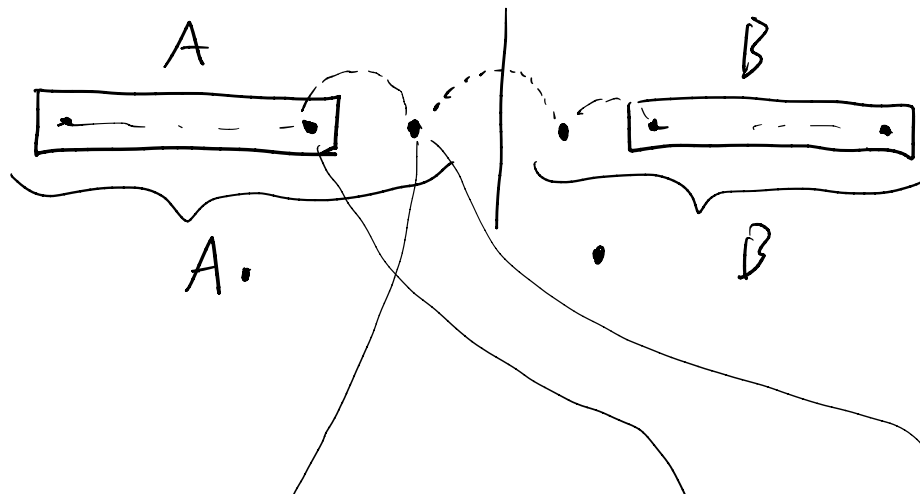
Concrete example: $H = \sum_{\vec{j}=1} \sum_{\alpha=x,y,z} J_{\alpha} S_{\alpha}^{(\vec{j})} S_{\alpha}^{(\vec{j}+1)}$ (xyz-model)
 (in 1D)
 $\uparrow$
 spin = $\frac{1}{2}$

- We exemplify the block growth procedure from length $\frac{N}{2}$ to $\frac{N}{2} + 1$.

$\hookrightarrow H_A, H_B, S_{\alpha}^{(\frac{N}{2})}, S_{\alpha}^{(\frac{N}{2}+1)}$ retrieved from memory
 $\uparrow$
 [in Block A] [in Block B]



add extra sites



↳ Build $H_{A\bullet} = H_A \otimes \overset{\downarrow}{1_2} + \sum_{\alpha} J_{\alpha} \overset{\downarrow}{S_{\alpha}^{(\frac{N}{2})}} \otimes \overset{\downarrow}{S_{\alpha}}$,

$$H_{\bullet B} = 1_2 \otimes H_B + \sum_{\alpha} J_{\alpha} S_{\alpha} \otimes S_{\alpha}^{(\frac{N}{2}+1)}$$

and with that $H_{A\bullet\bullet B} = H_{A\bullet} \otimes \underset{\uparrow \text{extra B}}{1_2} \otimes 1_B + 1_A \otimes \underset{\uparrow \text{extra A}}{1_2} \otimes H_{\bullet B} + \sum_{\alpha} J_{\alpha} 1_A \otimes S_{\alpha} \otimes S_{\alpha} \otimes 1_B$

(extra A) (extra B)

↳ Find ground state of $H_{A\bullet\bullet B}$ by Lanczos

Compute $H_{A\bullet\bullet B} |\Psi\rangle$ using the matrix representation Ψ_{ij} , i.e. no need to store explicitly $H_{A\bullet\bullet B}$ as a $(dx)^2 \times (dx)^2$ matrix.

(in A) (in B)

↳ Compute $\rho_A = \Psi \Psi^\dagger$ and $\rho_B = \Psi^\dagger \Psi$ --- (truncate)

↳ Eventually project $\Pi_A \otimes S_\alpha \rightarrow U^\dagger \Pi_A \otimes S_\alpha U$,
and $H_A \rightarrow U^\dagger H_A U$ into truncated basis and store
in memory (similar for B).

- Problems with infinite system DMRG

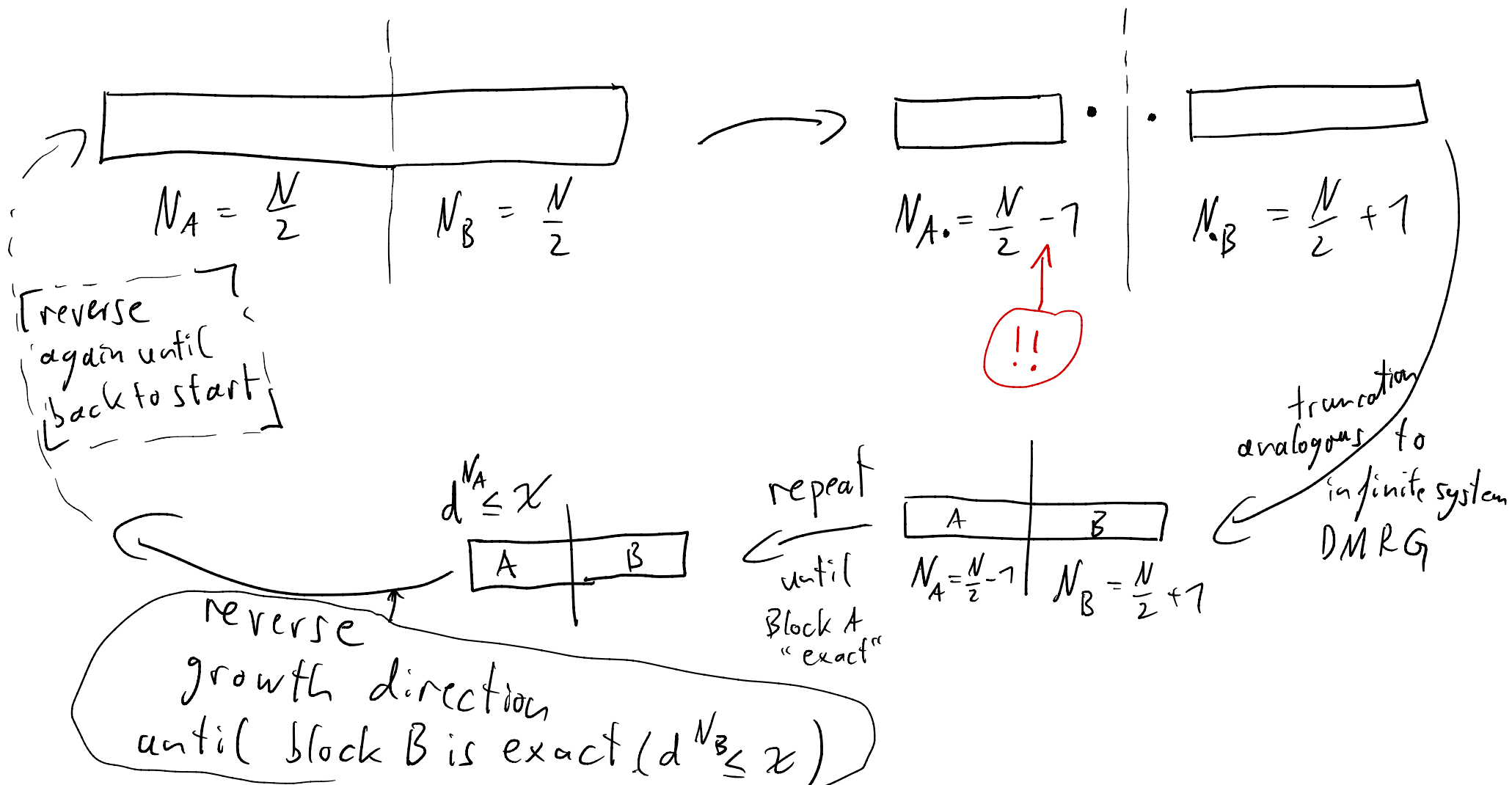
- System to be described by state $|\psi\rangle$ changes (grows)
during iteration $\leadsto$ This can lead to severe artefacts
and in some cases qualitatively wrong results.
- Even if $\frac{E}{N}$ is correct for $N \rightarrow \infty$, stopping at
finite N we cannot expect to have a good approxi-
mation of finite system with size N .

- Solution: Stop infinite system DMRG at desired finite N
and follow up with finite-system DMRG (see next page)

- Finite system DMRG algorithm:

- Proceed analogous to infinite system DMRG until size N is reached.

- Follow up with cyclic sweeps:

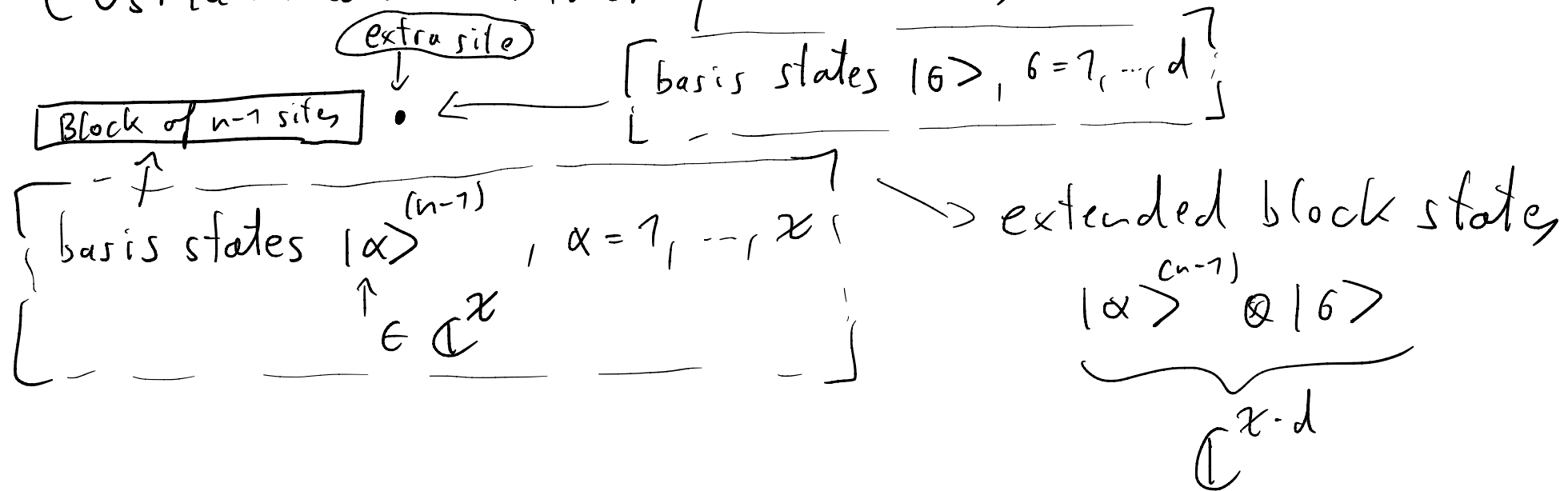


- Additional book-keeping : Representations of operators for all block sizes N_A , $N_B = N - N_A$ need to be stored in order to reconstruct $H_{A \dots B}$ during the sweeps.
- Overall computational cost per sweep $\mathcal{O}(N \cdot (x \cdot d)^3)$, typically 10 to 100 sweeps typically needed to achieve satisfactory convergence.

C.3: General Matrix Product State Methods

- Relation between DMRG truncation and MPS

(Östlund and Rommer, PRL 1995)



- DMRG truncation can be seen as a mapping from $\mathbb{C}^{x \cdot d} \rightarrow \mathbb{C}^x$ written as $|\alpha\rangle^{(n)} = \sum_{\beta, 6} A_{\alpha, \beta}^{(n), 6} |\beta\rangle^{(n-1)} \otimes |6\rangle$
- $\uparrow$
 $1, \dots, x$

- If $A^{(n)}$ becomes stationary at some $n_0 \gg 1$, we may express the basis states in the "bulk region" $n_0+1, \dots, n$ (with $A^6 := \left(A_{\alpha, \beta}^{(j), 6} \right)_{\alpha, \beta}$, $j > n_0$) as

$$|\alpha\rangle^{(n)} = \sum_{\beta_{n_0+1}, \dots, \beta_n} \left(A^{\beta_n} A^{\beta_{n-1}} \dots A^{\beta_{n_0+1}} \right)_{\alpha, \beta} |\beta\rangle^{(n_0)} | \beta_n, \dots, \beta_{n_0+1} \rangle$$

- A generic state for the bulk region may then be written as (shifting $n_0 \rightarrow 0$)

$$|\Psi_Q\rangle = \sum_{\{\beta_j\}} \text{Tr}(Q A^{\beta_n} \dots A^{\beta_1}) | \beta_n, \dots, \beta_1 \rangle.$$