

## Die Navier-Stokes-Gleichungen

### Darstellung in kartesischen Koordinaten

$$\rho \cdot \left( \frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) = \rho \cdot \vec{f}_m - \nabla p + \eta \cdot \Delta \vec{v} + \left( \zeta + \frac{1}{3} \cdot \eta \right) \cdot \nabla (\nabla \cdot \vec{v}) \quad \text{wobei: } \zeta = \lambda + \frac{2}{3} \cdot \eta \quad \left( \begin{array}{l} \zeta = \text{Druck-/Volumen-/Kompressions-/dilatorische/ zweite Zähigkeit;} \\ \lambda = \text{erste Lamé-Konstante} \end{array} \right)$$

Masse \* (lokale + konvektive Beschleunigung) = Raumkräfte + Druckkräfte + Widerstand zu Formänderung + Widerstand zur Volumenänderung

### Gleichungen für inkompressible Fluide:

$$\text{x-Richtung: } \rho \cdot \left( \frac{\partial v_x}{\partial t} + v_x \cdot \frac{\partial v_x}{\partial x} + v_y \cdot \frac{\partial v_x}{\partial y} + v_z \cdot \frac{\partial v_x}{\partial z} \right) = \rho \cdot f_x - \frac{\partial p}{\partial x} + \eta \cdot \left( \frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right)$$

$$\text{y-Richtung: } \rho \cdot \left( \frac{\partial v_y}{\partial t} + v_x \cdot \frac{\partial v_y}{\partial x} + v_y \cdot \frac{\partial v_y}{\partial y} + v_z \cdot \frac{\partial v_y}{\partial z} \right) = \rho \cdot f_y - \frac{\partial p}{\partial y} + \eta \cdot \left( \frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right)$$

$$\text{z-Richtung: } \rho \cdot \left( \frac{\partial v_z}{\partial t} + v_x \cdot \frac{\partial v_z}{\partial x} + v_y \cdot \frac{\partial v_z}{\partial y} + v_z \cdot \frac{\partial v_z}{\partial z} \right) = \rho \cdot f_z - \frac{\partial p}{\partial z} + \eta \cdot \left( \frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right)$$

### Darstellung in Zylinderkoordinaten (für inkompressible Fluide)

$$\text{r-Richtung: } \rho \cdot \left( \frac{\partial v_r}{\partial t} + v_r \cdot \frac{\partial v_r}{\partial r} + \frac{v_\phi}{r} \cdot \frac{\partial v_r}{\partial \phi} + v_z \cdot \frac{\partial v_r}{\partial z} - \frac{v_\phi^2}{r} \right) = \rho \cdot f_r - \frac{\partial p}{\partial r} + \eta \cdot \left( \frac{\partial^2 v_r}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial v_r}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2 v_r}{\partial \phi^2} + \frac{\partial^2 v_r}{\partial z^2} - \frac{v_r}{r^2} - \frac{2}{r^2} \cdot \frac{\partial v_\phi}{\partial \phi} \right)$$

$$\text{\theta-Richtung: } \rho \cdot \left( \frac{\partial v_\phi}{\partial t} + v_r \cdot \frac{\partial v_\phi}{\partial r} + \frac{v_\phi}{r} \cdot \frac{\partial v_\phi}{\partial \phi} + v_z \cdot \frac{\partial v_\phi}{\partial z} + \frac{v_r \cdot v_\phi}{r} \right) = \rho \cdot f_\phi - \frac{1}{r} \cdot \frac{\partial p}{\partial \phi} + \eta \cdot \left( \frac{\partial^2 v_\phi}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial v_\phi}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{\partial^2 v_\phi}{\partial z^2} - \frac{v_\phi}{r^2} + \frac{2}{r^2} \cdot \frac{\partial v_r}{\partial \phi} \right)$$

$$\text{z-Richtung: } \rho \cdot \left( \frac{\partial v_z}{\partial t} + v_r \cdot \frac{\partial v_z}{\partial r} + \frac{v_\phi}{r} \cdot \frac{\partial v_z}{\partial \phi} + v_z \cdot \frac{\partial v_z}{\partial z} \right) = \rho \cdot f_z - \frac{\partial p}{\partial z} + \eta \cdot \left( \frac{\partial^2 v_z}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial v_z}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2 v_z}{\partial \phi^2} + \frac{\partial^2 v_z}{\partial z^2} \right)$$

### Darstellung in Kugelkoordinaten (für inkompressible Fluide)

$$\text{r-Richtung: } \rho \cdot \left( \frac{\partial v_r}{\partial t} + v_r \cdot \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \cdot \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \cdot \sin \theta} \cdot \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \right) = \rho \cdot f_r - \frac{\partial p}{\partial r} + \eta \cdot \left[ \Delta v_r - \frac{2 \cdot v_r}{r^2} - \frac{2}{r^2 \cdot \sin^2 \theta} \cdot \frac{\partial (v_\theta \cdot \sin \theta)}{\partial \theta} - \frac{2}{r^2 \cdot \sin \theta} \cdot \frac{\partial v_\phi}{\partial \phi} \right]$$

$$\text{\theta-Richtung: } \rho \cdot \left( \frac{\partial v_\theta}{\partial t} + v_r \cdot \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \cdot \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \cdot \sin \theta} \cdot \frac{\partial v_\theta}{\partial \phi} + \frac{v_r \cdot v_\theta}{r} - \frac{v_\phi^2 \cdot \cot \theta}{r} \right) = \rho \cdot f_\theta - \frac{1}{r} \cdot \frac{\partial p}{\partial \theta} + \eta \cdot \left( \Delta v_\theta + \frac{2}{r^2} \cdot \frac{\partial v_r}{\partial \theta} - \frac{v_\theta}{r^2 \cdot \sin^2 \theta} - \frac{2 \cdot \cos \theta}{r^2 \cdot \sin^2 \theta} \cdot \frac{\partial v_\phi}{\partial \phi} \right)$$

$$\text{\phi-Richtung: } \rho \cdot \left( \frac{\partial v_\phi}{\partial t} + v_r \cdot \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \cdot \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \cdot \sin \theta} \cdot \frac{\partial v_\phi}{\partial \phi} + \frac{v_r \cdot v_\phi}{r} + \frac{v_\theta \cdot v_\phi \cdot \cot \theta}{r} \right) = \rho \cdot f_\phi - \frac{1}{r} \cdot \frac{\partial p}{\partial \phi} + \eta \cdot \left( \Delta v_\phi + \frac{2}{r^2 \cdot \sin \theta} \cdot \frac{\partial v_r}{\partial \phi} + \frac{2 \cdot \cos \theta}{r^2 \cdot \sin^2 \theta} \cdot \frac{\partial v_\theta}{\partial \phi} - \frac{v_\phi}{r^2 \cdot \sin^2 \theta} \right)$$

### Die Differentialoperatoren

#### kartesische Koordinaten:

Nabla - Operator:  
 (nur für kartes. Koordinaten)

$$\vec{\nabla} = e_x \cdot \frac{\partial}{\partial x} + e_y \cdot \frac{\partial}{\partial y} + e_z \cdot \frac{\partial}{\partial z}$$

Laplace - Operator:

$$\Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

Gradient eines Skalars:

$$\text{grad}(s) = \vec{\nabla} s = e_x \cdot \frac{\partial}{\partial x} s + e_y \cdot \frac{\partial}{\partial y} s + e_z \cdot \frac{\partial}{\partial z} s$$

Divergenz eines Vektors:

$$\text{div}(\vec{v}) = \vec{\nabla} \cdot \vec{v} = \frac{\partial}{\partial x} v_x + \frac{\partial}{\partial y} v_y + \frac{\partial}{\partial z} v_z$$

Divergenz eines Gradienten:

$$\text{div}(\text{grad}(s)) = \Delta s = \vec{\nabla} \cdot \vec{\nabla} s = \frac{\partial^2}{\partial x^2} s + \frac{\partial^2}{\partial y^2} s + \frac{\partial^2}{\partial z^2} s$$

#### Kugelkoordinaten:

$$\text{grad}(s) = e_r \cdot \frac{\partial}{\partial r} s + e_\theta \cdot \frac{1}{r} \cdot \frac{\partial}{\partial \theta} s + e_\phi \cdot \frac{1}{r \cdot \sin \theta} \cdot \frac{\partial}{\partial \phi} s$$

$$\text{div}(\vec{v}) = \frac{1}{r^2} \cdot \frac{\partial}{\partial r} (r^2 \cdot v_r) + \frac{1}{r \cdot \sin \theta} \cdot \frac{\partial}{\partial \theta} (\sin \theta \cdot v_\theta) + \frac{1}{r \cdot \sin \theta} \cdot \frac{\partial v_\phi}{\partial \phi}$$

$$\Delta = \frac{1}{r^2} \cdot \frac{\partial}{\partial r} \left( r^2 \cdot \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \cdot \sin \theta} \cdot \frac{\partial}{\partial \theta} \left( \sin \theta \cdot \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \cdot \sin^2 \theta} \cdot \frac{\partial^2}{\partial \phi^2}$$

#### Literatur:

L. D. Landau, E. M. Lifschitz. Lehrbuch der theoretischen Physik, Bd. 6, Hydrodynamik. Akademie Verlag, Berlin, 1991.